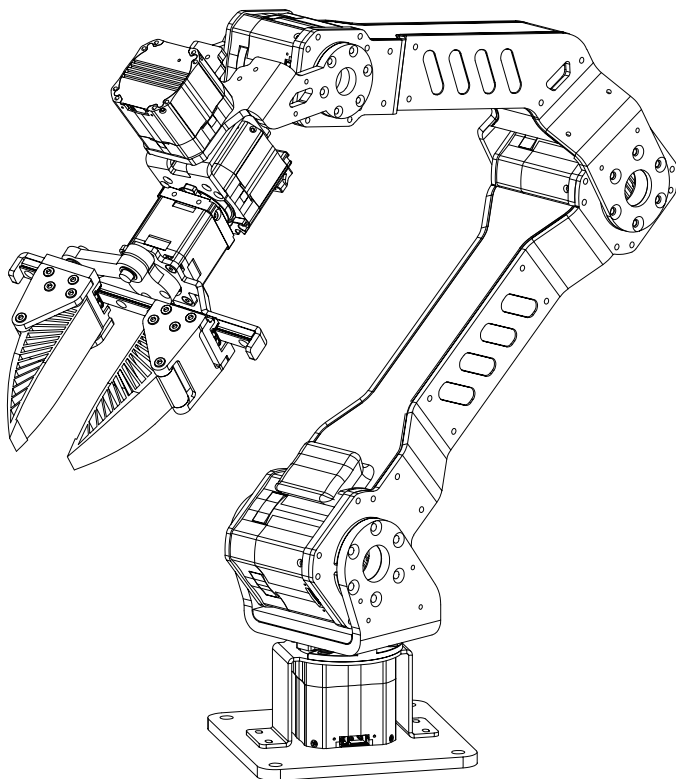


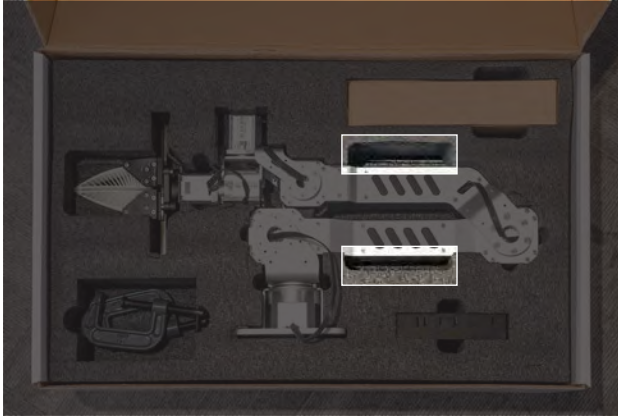
Panthera-HT Robotic Arm

Quick Start Guide



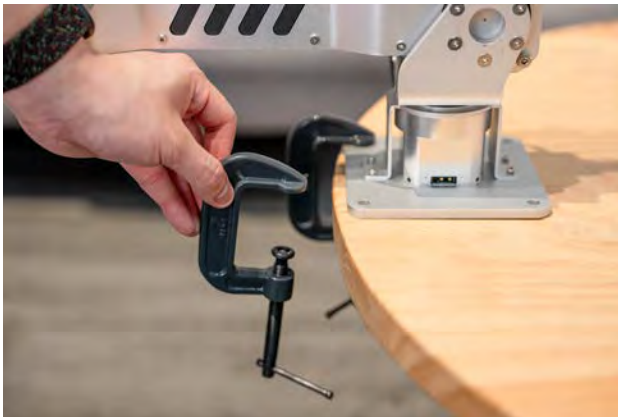
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I Step



The robotic arm's packaging box foam liner has a reserved opening for removing items. By inserting both hands into the slot and applying slight force, the product can be taken out.

II step



Place the product on a stable platform, and use G-type clamps (or the included screws) to secure the product to the platform.

III Step



Manually adjust the position of motor number 7 to set to zero

IV Step



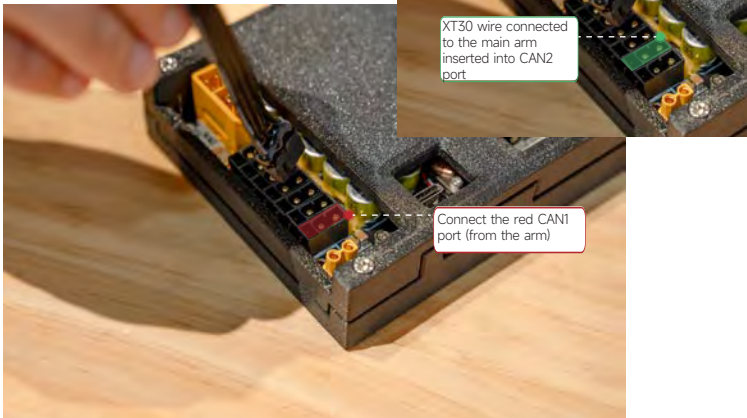
Manually adjust the position of Motor 1 to zero

V Step



Take out the included XT30 2-2 wiring harness, and connect one end to the product's motor No. 1.

VI Step



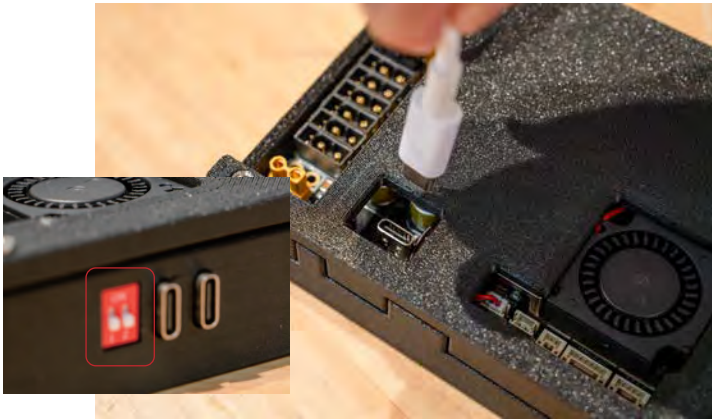
The other end of the wiring harness is connected to the 7-channel CAN port on the bottom plate of the universal box.

VII Step



Take out the USB to Type-C cable, and connect the USB end to the computer

VIII Step



Simultaneously toggle the DIP switches on the back of the motherboard down to turn them off, then you can use the Type-C port to connect to the Type-C port on the upper part of the universal box motherboard.

IX Step



Take out the power adapter and the matching connector

X Step



Connect the DC port with the DC to XT60 adapter

XI Step



Connect the adapter to the three-prong plug

XII Step



Insert the XT60 male plug into the XT60 port on the baseplate of the universal box

XIII Step



Connect the power supply and the adapter plug to provide power to the product

XIV Step



Briefly press the universal box button to open the base plate. The product will be powered on, after which subsequent development can proceed. Please pay attention to the product status during this period.




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